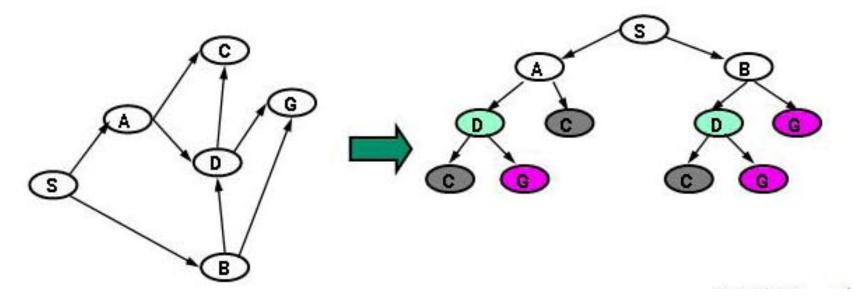
Review of BFS and DFS

305450 Lab01

Graph search as Tree search

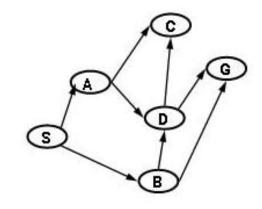
- Trees are directed graphs without cycles
- We can turn graph search problems into tree search problems by
 - Replacing undirected links by 2 directed links
 - Avoiding loops in paths (or keeping track of visited nodes)



Terminology

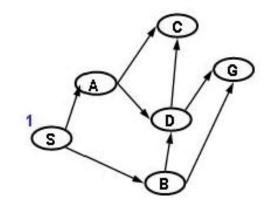
- Visited a state N is first visited when a path to N first gets added to Q.
 - We visited a state when place it on Q, but we have not yet generated its descendants
- Expanded a state N is expanded when it is the state of a node that is pulled of Q.
 - At this point, the descendants of N are visited and the path that led to M is extended to the descendants.
 - When a node M is expanded, we will not expand it again, hence we discard it from Q.

Q	Visited
1	
2	
3	
4	
5	



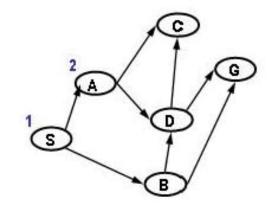
- Added path is in blue
- We show the paths in reversed order; the node's state is the first element

	Q	Visited
1	(S)	s
2		
3		
4		
5		



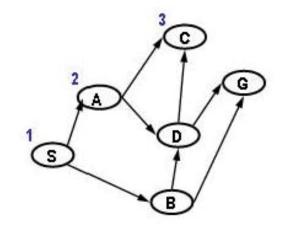
- Added path is in blue
- We show the paths in reversed order; the node's state is the first element

	Q	Visited
1	(S)	s
2	(A S) (B S)	A, B, S
3		
4		
5		



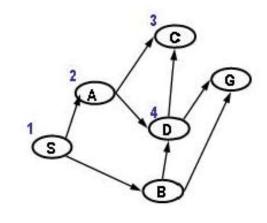
- Added path is in blue
- We show the paths in reversed order; the node's state is the first element

	Q	Visited
1	(S)	S
2	(A S) (B S)	A, B, S
3	(C A S) (D A S) (B S)	C,D,B,A,S
4		
5		



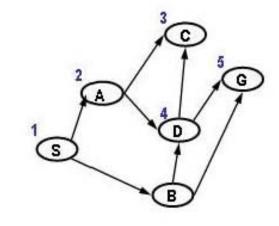
- Added path is in blue
- We show the paths in reversed order; the node's state is the first element

	Q	Visited
1	(S)	S
2	(A S) (B S)	A, B, S
3	(C A S) (D A S) (B S)	C,D,B,A,S
4	(D A S) (B S)	C,D,B,A,S
5		



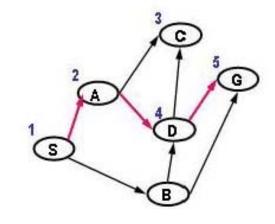
- Added path is in blue
- We show the paths in reversed order; the node's state is the first element

	Q	Visited
1	(S)	s
2	(A S) (B S)	A, B, S
3	(C A S) (D A S) (B S)	C,D,B,A,S
4	(D A S) (B S)	C,D,B,A,S
5	(G D A S) (B S)	G,C,D,B,A,S

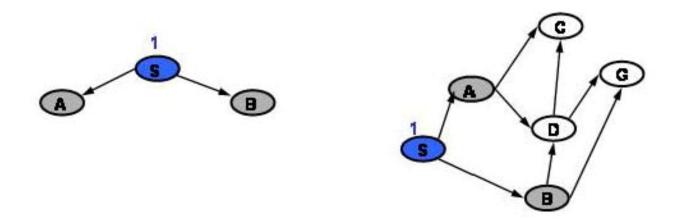


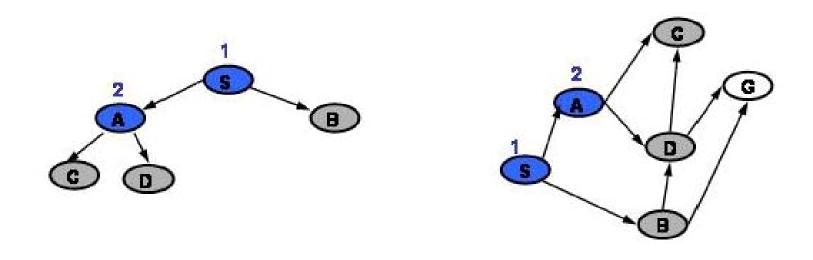
- Added path is in blue
- We show the paths in reversed order; the node's state is the first element

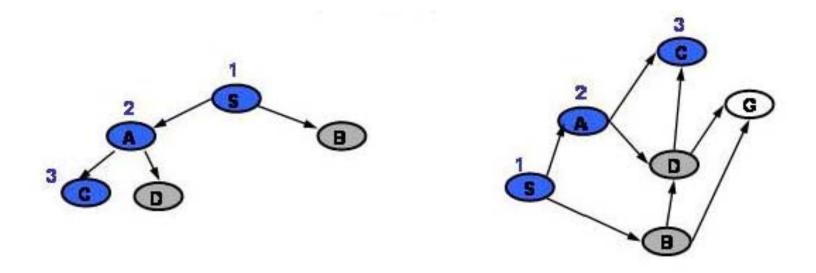
	Q	Visited
1	(S)	S
2	(A S) (B S)	A, B, S
3	(C A S) (D A S) (B S)	C,D,B,A,S
4	(D A S) (B S)	C,D,B,A,S
5	(GDAS) (BS)	G,C,D,B,A,S

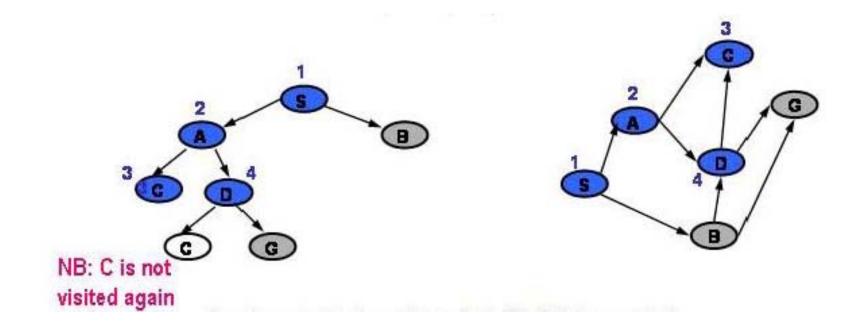


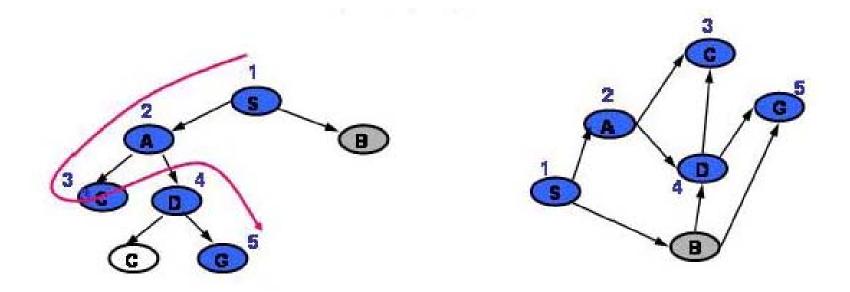
- Added path is in blue
- We show the paths in reversed order; the node's state is the first element





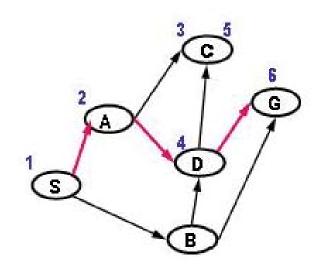




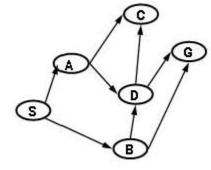


Depth First Search (without Visited list)

	Q
1	(S)
2	(A S) (B S)
3	(C A S) (D A S) (B S)
4	(D A S) (B S)
5	(C D A S) (G D A S) (B S)
6	(G D A S) (B S)

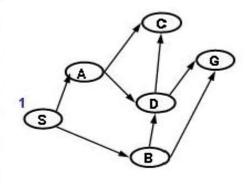


	Q	Visited
1	(S)	s
2		
3		
4		
5		
6		



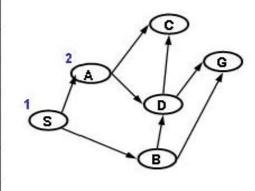
- Added path is in blue
- We show the paths in reversed order; the node's state is the first element

	Q	Visited
1	(S)	s
2	(A S) (B S)	A,B,S
3		
4		
5		
6		



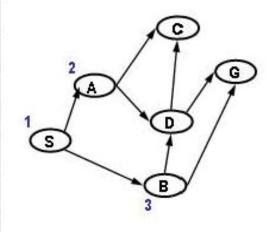
- Added path is in blue
- We show the paths in reversed order; the node's state is the first element

	Q	Visited
1	(S)	s
2	(A S) (B S)	A,B,S
3	(B S) (C A S) (D A S)	C,D,B,A,S
4		
5		
6		



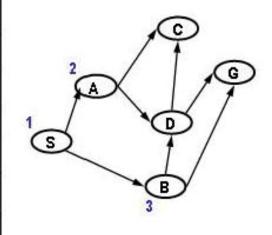
- Added path is in blue
- We show the paths in reversed order; the node's state is the first element

	Q	Visited
1	(S)	s
2	(A S) (B S)	A,B,S
3	(BS) (CAS) (DAS)	C,D,B,A,S
4	(C A S) (D A S) (G B S)*	G,C,D,B,A,S
5		
6		



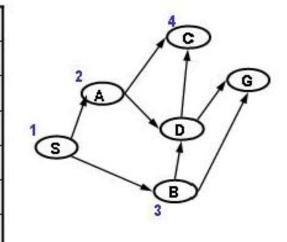
- Added path is in blue
- We show the paths in reversed order; the node's state is the first element

	Q	Visited
1	(S)	s
2	(A S) (B S)	A,B,S
3	(B S) (C A S) (D A S)	C,D,B,A,S
4	(C A S) (D A S) (G B S)*	G,C,D,B,A,S
5		
6		



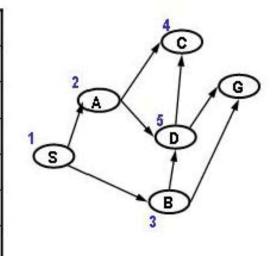
- Added path is in blue
- We show the paths in reversed order; the node's state is the first element

	Q	Visited
1	(S)	s
2	(A S) (B S)	A,B,S
3	(B S) (C A S) (D A S)	C,D,B,A,S
4	(C A S) (D A S) (G B S)*	G,C,D,B,A,S
5	(D A S) (G B S)	G,C,D,B,A,S
6		



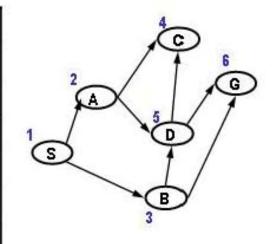
- Added path is in blue
- We show the paths in reversed order; the node's state is the first element

	Q	Visited
1	(S)	Visited S A,B,S C,D,B,A,S G,C,D,B,A,S
2	(A S) (B S)	A,B,S
3	(B S) (C A S) (D A S)	C,D,B,A,S
4	(C A S) (D A S) (G B S)*	G,C,D,B,A,S
5	(D A S) (G B S)	G,C,D,B,A,S
6		



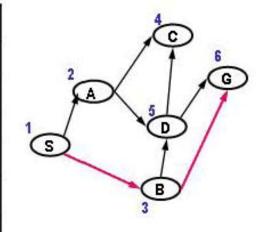
- Added path is in blue
- We show the paths in reversed order; the node's state is the first element

	Q	Visited
1	(S)	s
2	(A S) (B S)	A,B,S
3	(BS) (CAS) (DAS)	C,D,B,A,S
4	(C A S) (D A S) (G B S)*	G,C,D,B,A,S
5	(D A S) (G B S)	G,C,D,B,A,S
6	(GBS)	G,C,D,B,A,S

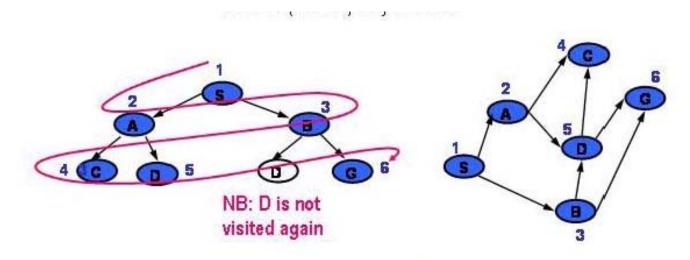


- Added path is in blue
- We show the paths in reversed order; the node's state is the first element

	Q	Visited
1	(S)	S
2	(A S) (B S)	A,B,S
3	(B S) (C A S) (D A S)	C,D,B,A,S
4	(C A S) (D A S) (G B S)*	G,C,D,B,A,S
5	(D A S) (G B S)	G,C,D,B,A,S
6	(GBS)	G,C,D,B,A,S



- Added path is in blue
- We show the paths in reversed order; the node's state is the first element



- Added path is in blue
- We show the paths in reversed order; the node's state is the first element

Breath First Search (without Visited list)

4 (C A S) (D A S) (D B S) (G B S)* 5 (D A S) (D B S) (G B S)		Q
3 (B S) (C A S) (D A S) 4 (C A S) (D A S) (D B S) (G B S)* 5 (D A S) (D B S) (G B S)	1	(S)
4 (C A S) (D A S) (D B S) (G B S)* 5 (D A S) (D B S) (G B S)	2	(A S) (B S)
5 (D A S) (D B S) (G B S)	3	(B S) (C A S) (D A S)
	4	(C A S) (D A S) (D B S) (G B S)*
6 (D B S) (G B S) (C D A S) (G D A S)	5	(D A S) (D B S) (G B S)
	6	(D B S) (G B S) (C D A S) (G D A S)
7 (GBS) (CDAS) (GDAS) (CDBS) (GDBS)	7	(G B S) (C D A S) (G D A S) (C D B S) (G D B S)

- Added path is in blue
- We show the paths in reversed order; the node's state is the first element
- We could have stopped here, when the fist path to the goal was generated